

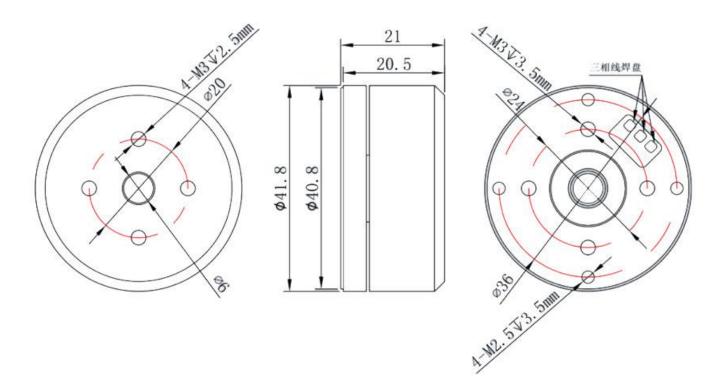
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| Item | Specifications |
|-------------------------------------|----------------------|
| Resistance/Line | 3.5 Ω |
| Inductance/Line | 2.1 mH |
| KV | KV100 |
| Torque constant | 0.15 Nm/A |
| Rotor inertia | 61 g/cm ² |
| IP Class | IP45 |
| Magnet temperature resistance class | H 180° C |



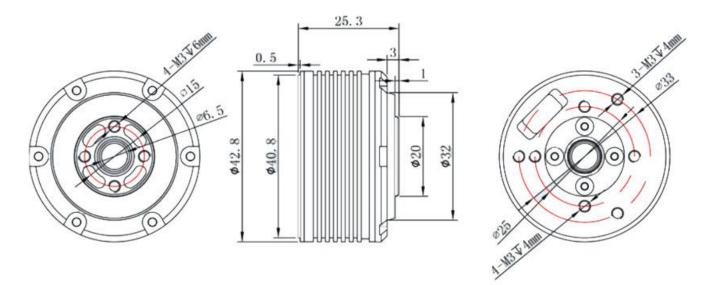


| Item | M016BE0150-41-21 |
|--------------------|------------------|
| Number of poles | 12N14P |
| Voltage (VDC) | 16 |
| Rated Current (A) | 1.45 |
| Rated Torque (N·m) | 0.15 |
| Rated speed (rpm) | 900 |
| Peak Current (A) | 4.5 |
| Peak Torque (N·m) | 0.46 |
| Body Length (mm) | 21 |
| Weight (g) | 90 |





| Item | Specifications |
|-----------------|------------------------|
| Resistance/Line | 1.53 Ω |
| Inductance/Line | 0.33 uH |
| Speed constant | 290 rpm/V |
| Torque constant | 0.33 Nm/A |
| Rotor inertia | 24.2 g/cm ² |



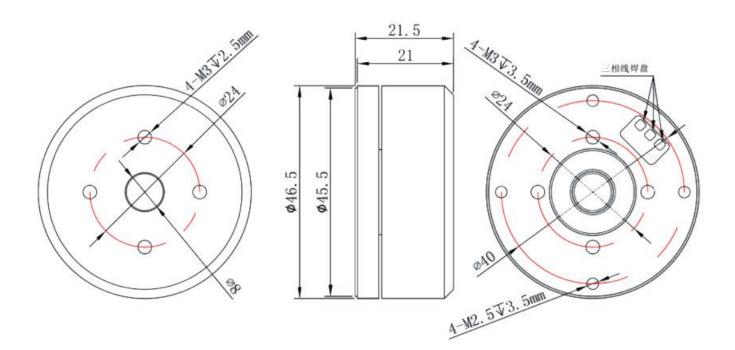


| Item | M012BI0080-42-25 |
|-------------------------|------------------|
| Number of Poles | 7 |
| Voltage (VDC) | 12 |
| Rated Current (A) | 2.3 |
| Rated Torque (N·m) | 0.08 |
| Rated speed (rpm) | 2200 |
| Max. no-load speed(rpm) | 3480 |
| Peak Torque (N·m) | 0.28 |
| Peak Current (A) | 8.5 |
| Body Length (mm) | 25 |
| Weight (g) | 83 |





| Item | Specifications |
|-------------------------------------|----------------------|
| Resistance/Line | 4.5 Ω |
| Inductance/Line | 1.8 mH |
| KV | KV70 |
| Torque constant | 0.14 Nm/A |
| Rotor inertia | 74 g/cm ² |
| IP Class | IP45 |
| Magnet temperature resistance class | H 180° C |



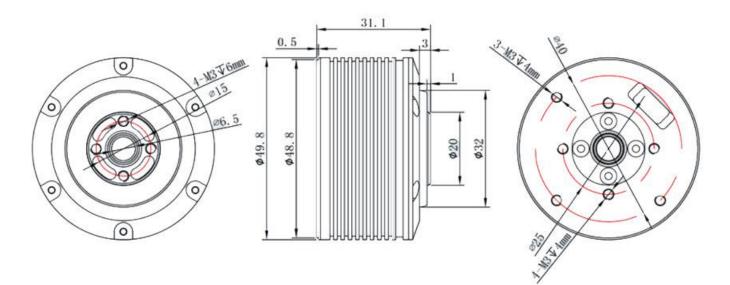


| Item | M016BE0250-46-21 |
|--------------------|------------------|
| Number of poles | 24N28P |
| Voltage (VDC) | 16 |
| Rated Current (A) | 1.65 |
| Rated Torque (N·m) | 0.25 |
| Rated speed (rpm) | 600 |
| Peak Current (A) | 5 |
| Peak Torque (N·m) | 0.73 |
| Body Length (mm) | 21 |
| Weight (g) | 107 |





| Item | Specifications |
|-----------------|----------------------|
| Resistance/Line | 1.53 Ω |
| Inductance/Line | 2.1 uH |
| Speed constant | 100 rpm/V |
| Torque constant | 0.1 Nm/A |
| Rotor inertia | 61 g/cm ² |



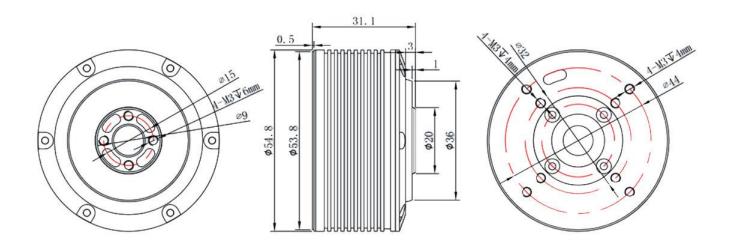


| Item | M016BI0150-49-31 |
|-------------------------|------------------|
| Number of Poles | 7 |
| Voltage (VDC) | 16 |
| Rated Current (A) | 1.45 |
| Rated Torque (N·m) | 0.15 |
| Rated speed (rpm) | 900 |
| Max. no-load speed(rpm) | 1500 |
| Peak Torque (N·m) | 0.46 |
| Peak Current (A) | 4.5 |
| Body Length (mm) | 31 |
| Weight (g) | 83 |





| Item | Specifications |
|-----------------|----------------------|
| Resistance/Line | 3.6 Ω |
| Inductance/Line | 1.8 uH |
| Speed constant | 70 rpm/V |
| Torque constant | 0.14 Nm/A |
| Rotor inertia | 74 g/cm ² |





| Item | M016BI0250-54-31 |
|-------------------------|------------------|
| Number of Poles | 14 |
| Voltage (VDC) | 16 |
| Rated Current (A) | 1.65 |
| Rated Torque (N·m) | 0.25 |
| Rated speed (rpm) | 600 |
| Max. no-load speed(rpm) | 1050 |
| Peak Torque (N·m) | 0.73 |
| Peak Current (A) | 5 |
| Body Length (mm) | 31 |
| Weight (g) | 183 |





Compact structure:

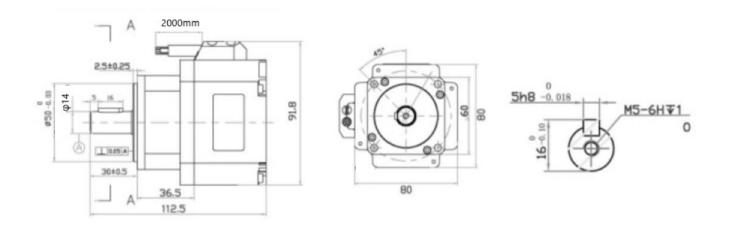
The product integrates servo driver and low-voltage servo motor into one, which is smaller in size and saves equipment installation space.

High reliability:

Eliminate the connection line between motor and driver, reduce equipment failure caused by connection problems, and reduce equipment failure rate.

Lower cost:

Save connection cables, effectively reducing equipment costs.



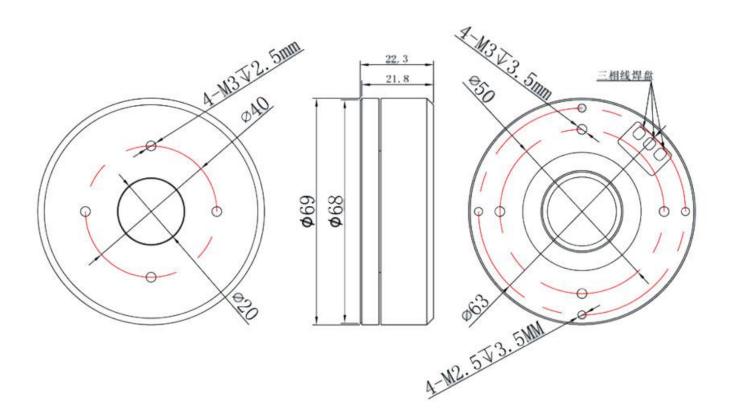


| Product Features | |
|-----------------------|---|
| Rated voltage | DC24V/DC48 |
| Protection class | IP20 |
| Rated output power | 200W/400W |
| Operating temperature | 0-40°C |
| Rated torque | 0.637/1.274 N.m |
| Rated speed | 3000 rpm |
| Rated input current | 10 A |
| Working Environment | The rated working altitude is below 1000m, when the |
| | working altitude is above 1000m, for every 100m rise, |
| | 1.5% reduction should be used.Maximum working |
| | altitude 4000m. |
| Life | >5,000h |
| Control method | Torque command, speed command, position command |
| Communication method | RS485、CAN |
| I0/AD/PWM | 3/1/1 |
| Protection function | Overvoltage, undervoltage, overcurrent, overload, |
| | blocking, phase loss |





| Item | Specifications |
|-------------------------------------|-----------------------|
| Resistance/Line | 5.5 Ω |
| Inductance/Line | 2.72 mH |
| KV | KV25 |
| Torque constant | 0.4 Nm/A |
| Rotor inertia | 355 g/cm ² |
| IP Class | IP45 |
| Magnet temperature resistance class | E 180°C |



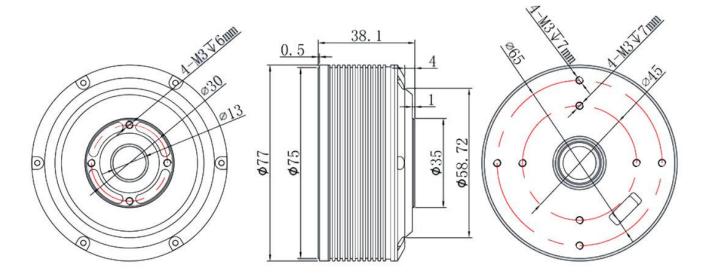


| Item | M024BE0600-69-22 |
|--------------------|------------------|
| Number of poles | 24N28P |
| Voltage (VDC) | 24 |
| Rated Current (A) | 1.43 |
| Rated Torque (N·m) | 0.6 |
| Rated speed (rpm) | 350 |
| Peak Current (A) | 4.2 |
| Peak Torque (N·m) | 1.75 |
| Body Length (mm) | 22 |
| Weight (g) | 230 |





| Item | Specifications |
|-----------------|-----------------------|
| Resistance/Line | 1.1 Ω |
| Inductance/Line | 0.9 uH |
| Speed constant | 55 rpm/V |
| Torque constant | 0.188 Nm/A |
| Rotor inertia | 355 g/cm ² |





| Item | M024BI0600-77-38 |
|-------------------------|------------------|
| Number of Poles | 14 |
| Voltage (VDC) | 24 |
| Rated Current (A) | 3.1 |
| Rated Torque (N·m) | 0.6 |
| Rated speed (rpm) | 850 |
| Max. no-load speed(rpm) | 1150 |
| Peak Torque (N·m) | 1.75 |
| Peak Current (A) | 9.5 |
| Body Length (mm) | 38 |
| Weight (g) | 364 |





Compact structure:

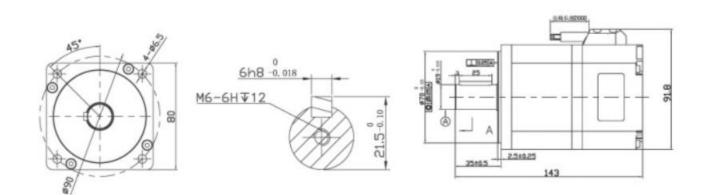
The product integrates servo driver and lowvoltage servo motor into one, which is smaller in size and saves equipment installation space.

High reliability:

Eliminate the connection line between motor and driver, reduce equipment failure caused by connection problems, and reduce equipment failure rate.

Lower cost:

Save connection cables, effectively reducing equipment costs.



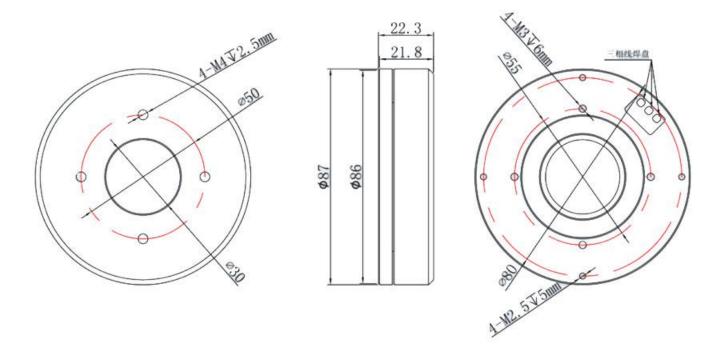


| Product Features | |
|-----------------------|---|
| Rated voltage | DC24V/DC48 |
| Protection class | IP20 |
| Rated output power | 200W/400W |
| Operating temperature | 0-40°C |
| Rated torque | 0.637/1.274 N.m |
| Rated speed | 3000 rpm |
| Rated input current | 10 A |
| Working Environment | The rated working altitude is below 1000m, when the |
| | working altitude is above 1000m, for every 100m rise, |
| | 1.5% reduction should be used.Maximum working |
| | altitude 4000m. |
| Life | >5,000h |
| Control method | Torque command, speed command, position command |
| Communication method | RS485、CAN |
| I0/AD/PWM | 3/1/1 |
| Protection function | Overvoltage, undervoltage, overcurrent, overload, |
| | blocking, phase loss |





| Item | Specifications |
|-------------------------------------|-----------------------|
| Resistance/Line | 1.8 Ω |
| Inductance/Line | 1.1 mH |
| KV | KV30 |
| Torque constant | 0.17 Nm/A |
| Rotor inertia | 650 g/cm ² |
| IP Class | IP45 |
| Magnet temperature resistance class | E 150°C |





| Item | M024BE1000-87-22 |
|--------------------|------------------|
| Number of poles | 36N42P |
| Voltage (VDC) | 24 |
| Rated Current (A) | 2.8 |
| Rated Torque (N·m) | 1 |
| Rated speed (rpm) | 450 |
| Peak Current (A) | 8.3 |
| Peak Torque (N·m) | 2.9 |
| Body Length (mm) | 22 |
| Weight (g) | 315 |